

ULTRA-LOW-POWER CMOS LOGIC

UNIVERSIDADE FEDERAL DE SANTA CATARINA
INTEGRATED CIRCUITS LABORATORY



Luiz Alberto Pasini Melek
Márcio Cherem Schneider
Carlos Galup-Montoro,
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PORTO GALINHAS



OUTLINE:

- Introduction
- CMOS Logic Gates Operating in Weak Inversion
- Substrate Bias Compensation Technique
- Conclusion

Introduction

- Continuous increase in use of portable electronics
- Battery operated → low power consumption → CMOS
- Total Power = Dynamic Power + Static Power

$$P_{DYN} \propto V_{DD}^2$$

$$P_{ST} \propto V_{DD}$$

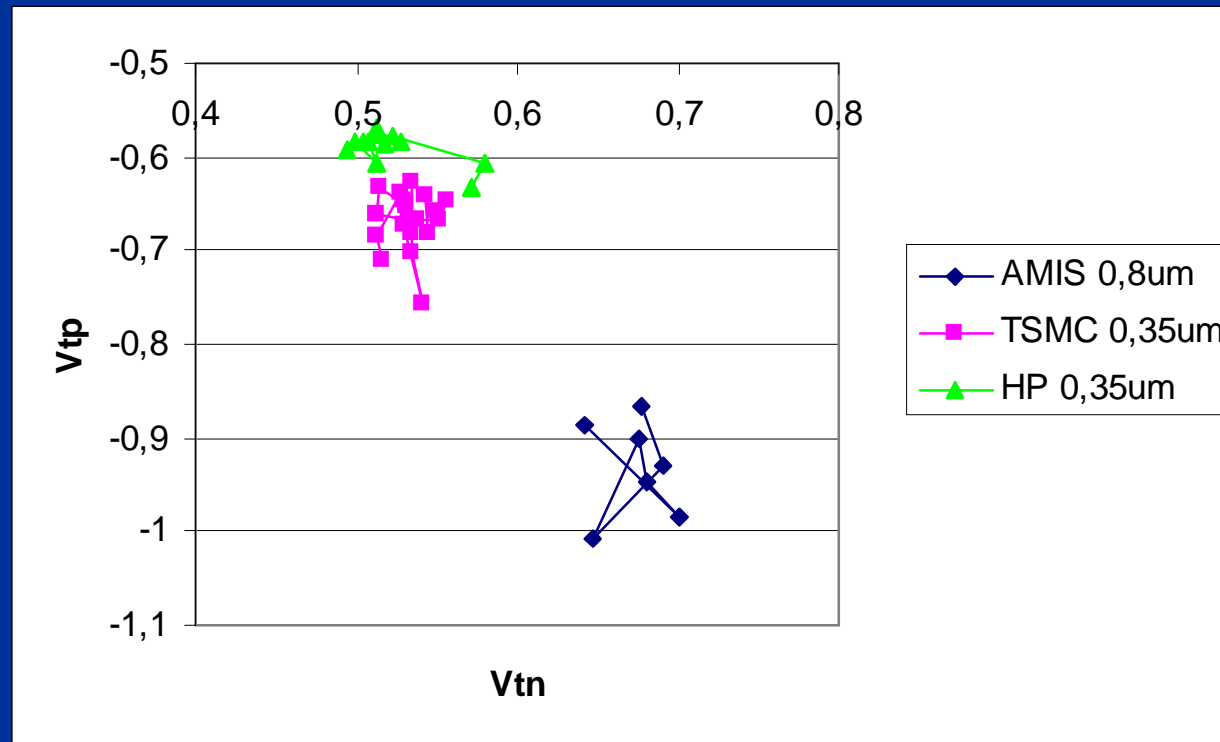
- Low Consumption → Low Supply Voltage + Low Operating Frequency



Subthreshold or Weak inversion (W.I.) operation

Technological Parameter Variations

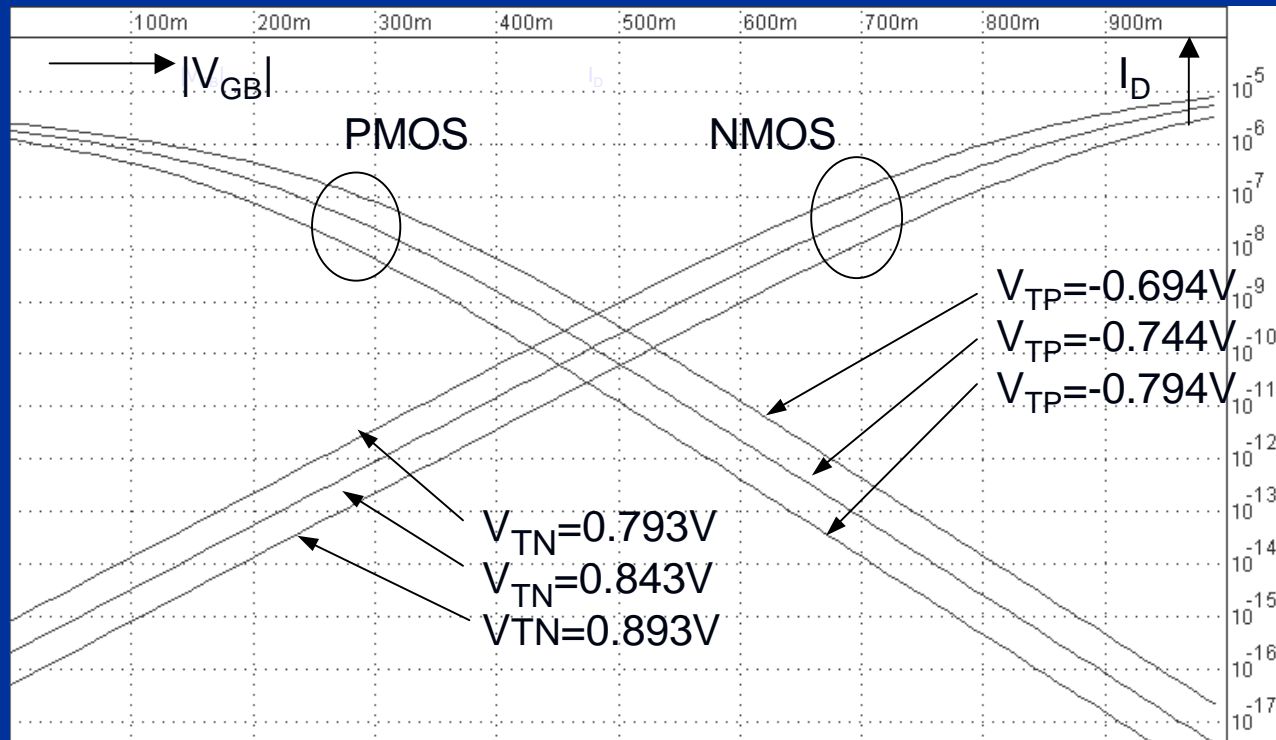
- *intrachip* parameter variation and *interchip* parameter variation → $\pm 100\text{mV}$ Threshold Voltage
 $\pm 30\%$ Current Factor



Consequences of Technological Parameter Variations

- Weak inversion → exponential current law

$$I_{DN(P)} = I_{ON(P)} \exp\left(-\frac{V_{GB} - V_{TN(P)} - n_{N(P)} \cdot V_{SB}}{n_{N(P)} \cdot \phi_T}\right) \left[1 - \exp\left(-\left(+\right) \frac{V_{DS}}{\phi_T}\right)\right]$$

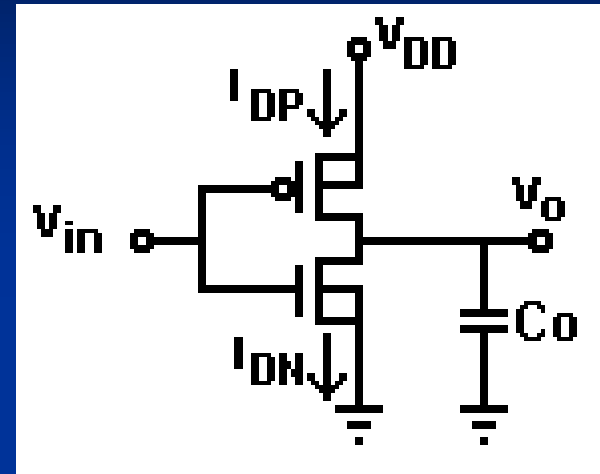


AMS0.8um

BSIM3v3

(W/L)=2um/0.8um

CMOS logic gates operating in weak inversion

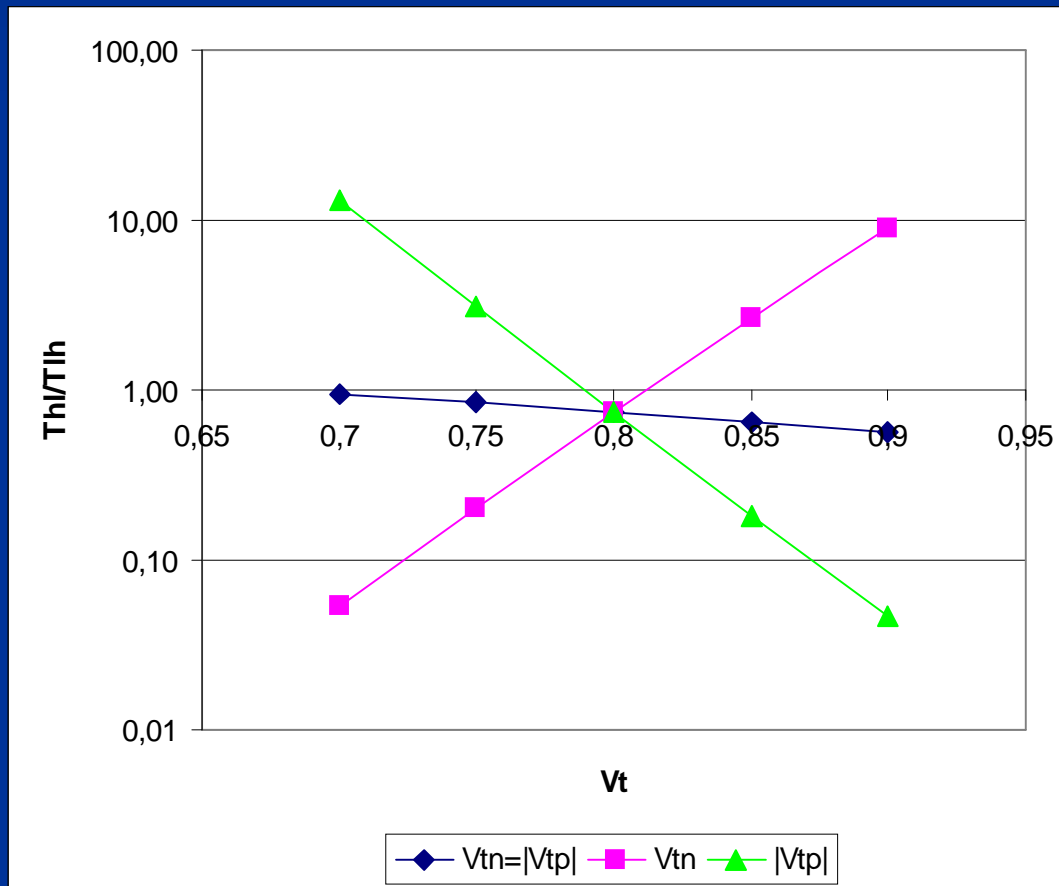


- Rise Time (TLH) and Fall Time (THL) – 10%-90%

$$I_{DN(P)} = -(+)C_o \cdot \frac{dV_o}{dt}$$

$$t_{HL(LH)} = \frac{0.8 C_o V_{DD}}{I_{ON(P)} e^{\frac{V_{DD} - |V_{TN(P)}|}{n_{N(P)} \phi_T}}}$$

Consequences of Technological Parameter Variations



INVERTER

0.8 μ m BET Technology

$$V_{TN} = |V_{TP}| = 0.8V$$

$$(W/L)_N = 15\mu/9\mu$$

$$(W/L)_P = 45\mu/9\mu$$

$$C_0 = 1.3pF$$

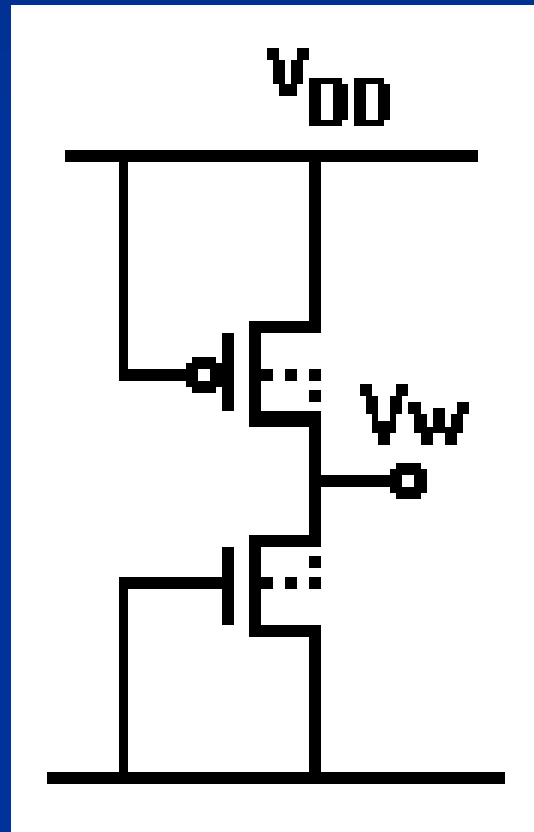
$$I_{ON} \approx I_{OP}$$

$$T_{HL}/T_{LH}|_{max} = 400 !!!$$

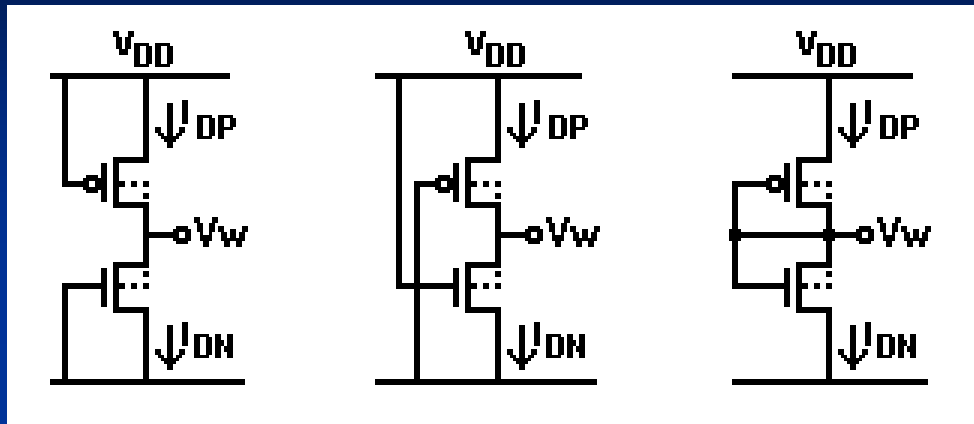
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Bryant, 2001

- Substrate Bias Circuit: NMOS and PMOS are “cut off”!?.



Proposed Compensation Technique



Bryant

Crossed

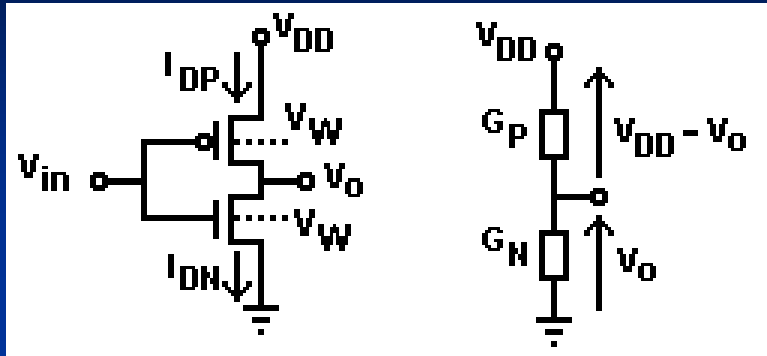
In between

$$I_{DP} = I_{DN}$$

$$V_w = \frac{V_{DD}}{2} + \frac{V_{TN}}{2 \cdot n_N} - \frac{|V_{TP}|}{2 \cdot n_{PT}} + \frac{\phi_T}{2} \ln \left(\frac{I_{OP}}{I_{ON}} \right)$$

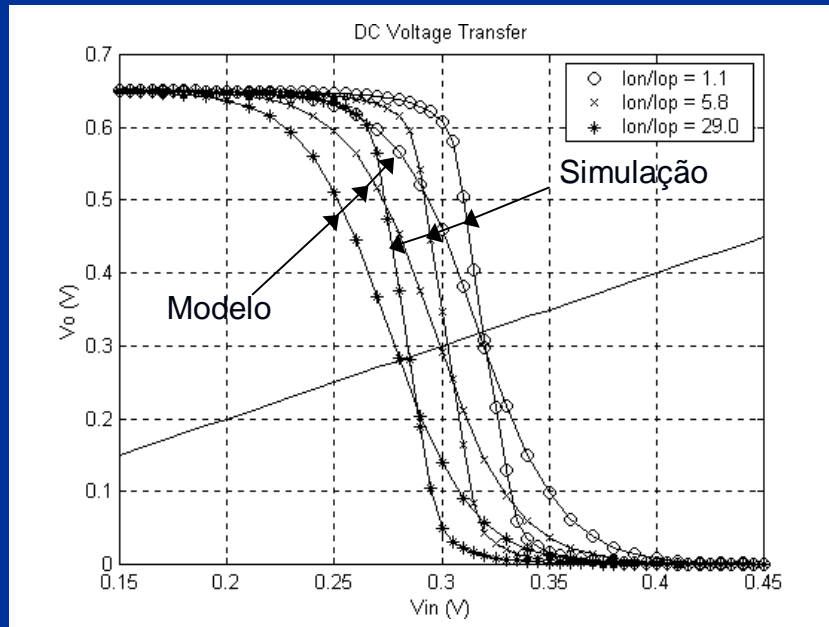
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DC Transfer characteristic for the Inverter



$$V_O = \frac{V_{DD}}{1 + e^{\frac{V_{IN} - V_{TH}}{\phi_T} \left(\frac{1}{n_N} + \frac{1}{n_P} \right)}}$$

$$V_{TH} = V_W = \frac{V_{DD}}{2} + \frac{V_{TN}}{2 \cdot n_N} - \frac{|V_{TP}|}{2 \cdot n_{PT}} + \frac{\phi_T}{2} \ln \left(\frac{I_{OP}}{I_{ON}} \right)$$



0.8μm AMS Technology
ACM MOSFET Model
VDD = 650mV
(W/L)_N=(W/L)_P = 2μm/0.8μm

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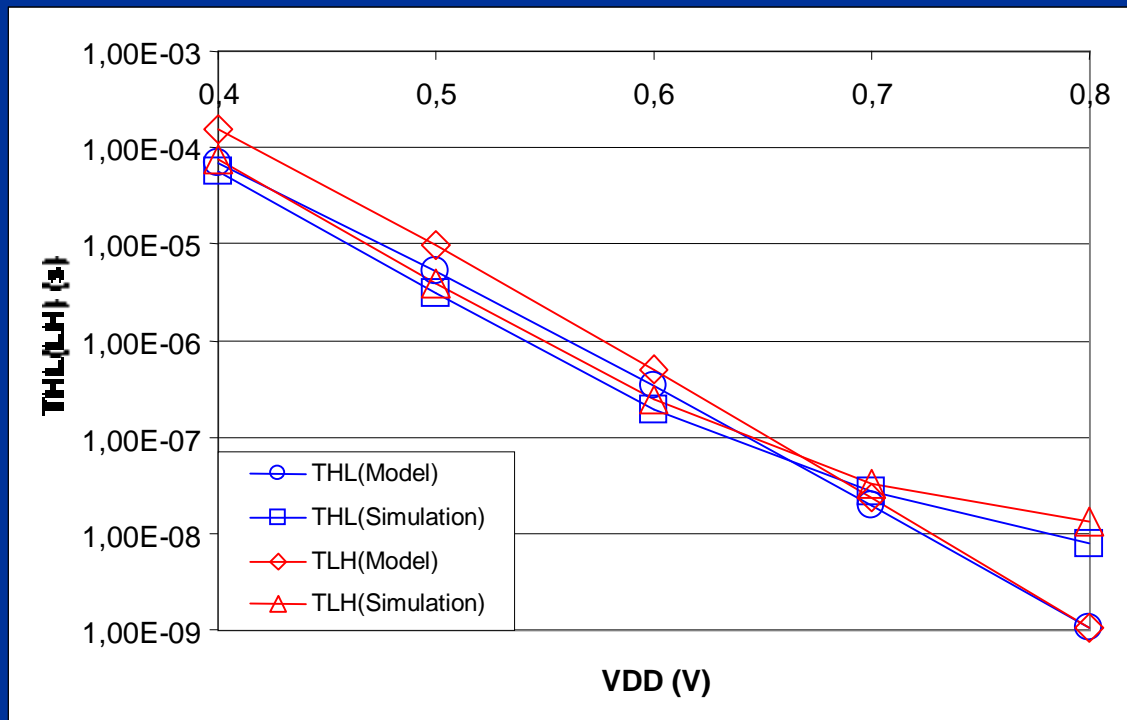
Inverter Transient

$$T_{HL(LH)} = \frac{0.8 C_O V_{DD}}{I_{DRIVE,N(P)}}$$

$$I_{DRIVE,N} = I_{ON} \cdot e^{\frac{V_{DD} - V_{TN} + V_W \cdot (n_N - 1)}{n_N \cdot \phi_T}}$$

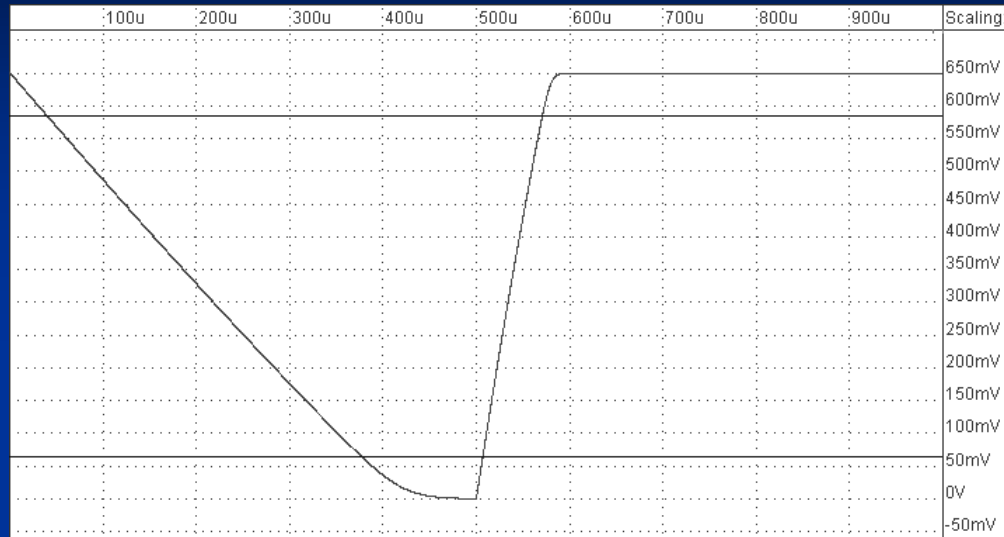
$$I_{DRIVE,P} = I_{OP} \cdot e^{\frac{n_P \cdot V_{DD} - |V_{TP}| - V_W \cdot (n_P - 1)}{n_P \cdot \phi_T}}$$

0.8μm AMS



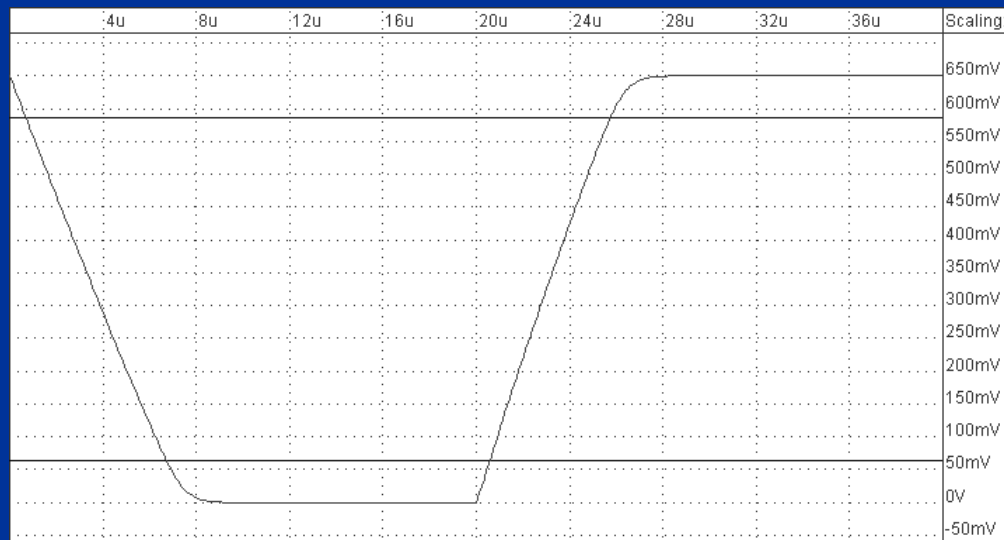
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Inverter Transient (II)



**0.8μm AMS
ACM model**
 $(W/L)_N = 2\mu\text{m}/0.8\mu\text{m}$
 $(W/L)_P = 2\mu\text{m}/0.8\mu\text{m}$

Without compensation
X axis : 1000μs
fMAX = 2.5kHz



With compensation
X axis : 40μs
fMAX = 88kHz

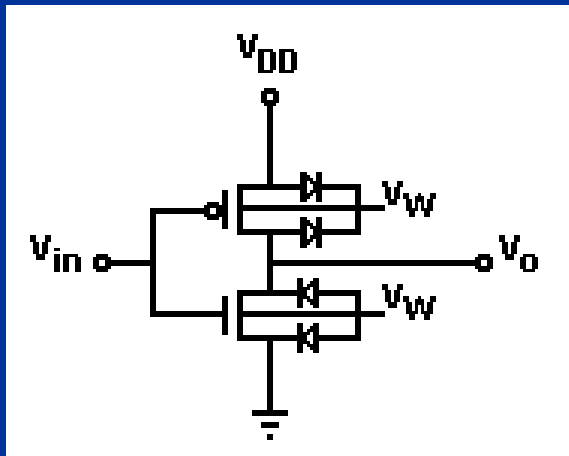
Power consumption

Dynamic Power

$$P_{DIN} = C_O \cdot V_{DD}^2 \cdot f$$

Static power → Diodes are forward biased

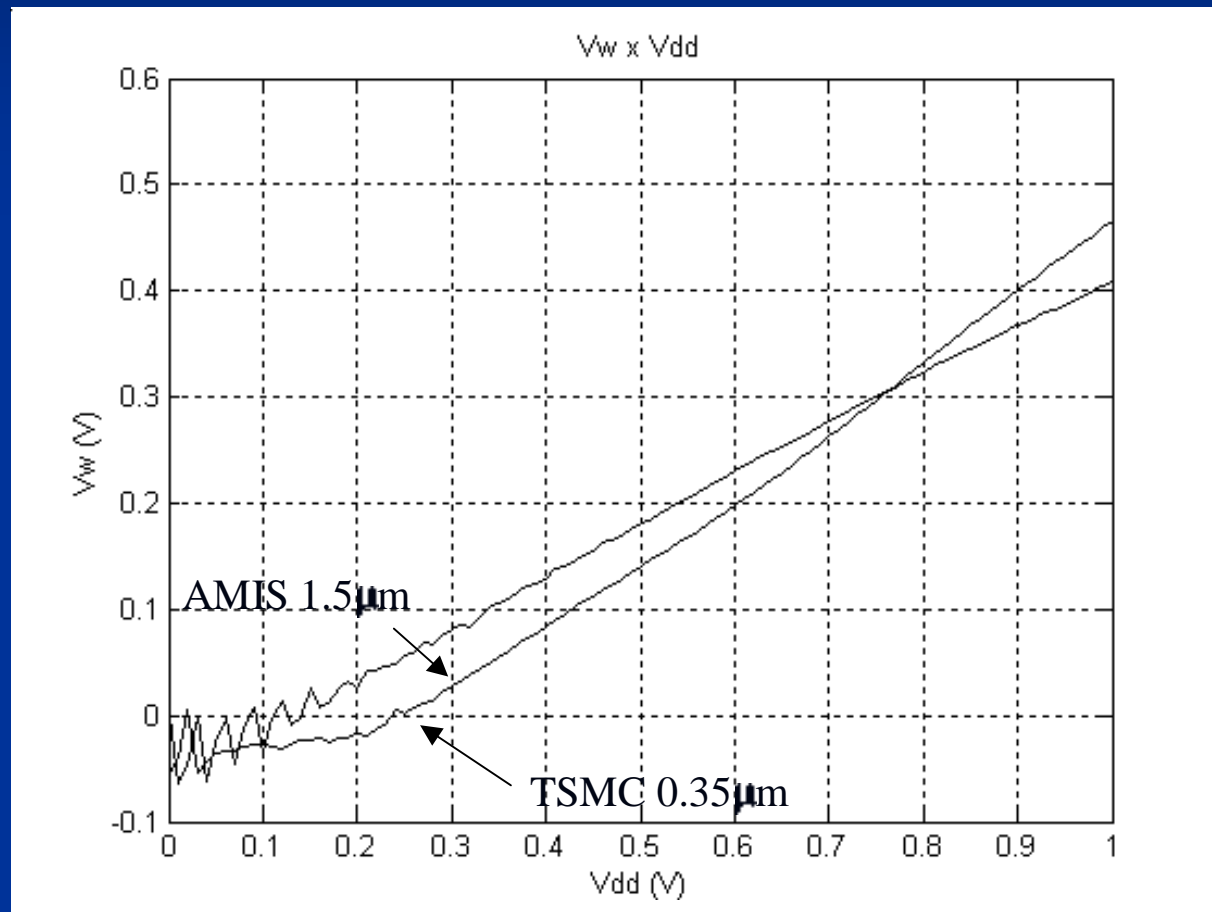
PTRANSISTORS << PDIODOS



$$P_{static} = \frac{3 \cdot V_{DD}}{2} \cdot e^{\frac{V_{DD}}{2 \cdot \phi_T}} \cdot (I_{SN} + I_{SP})$$

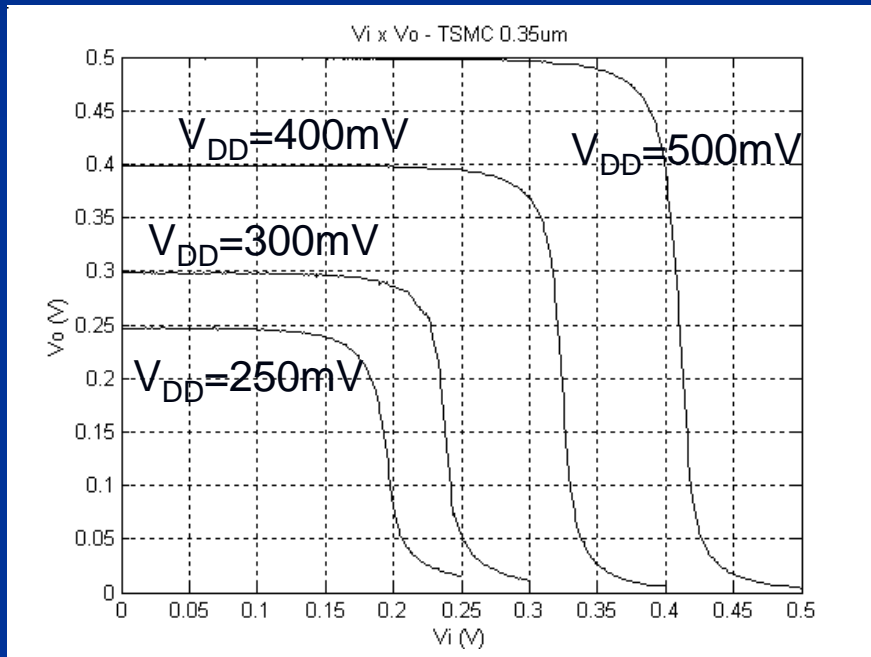
Experimental results

V_w BIAS

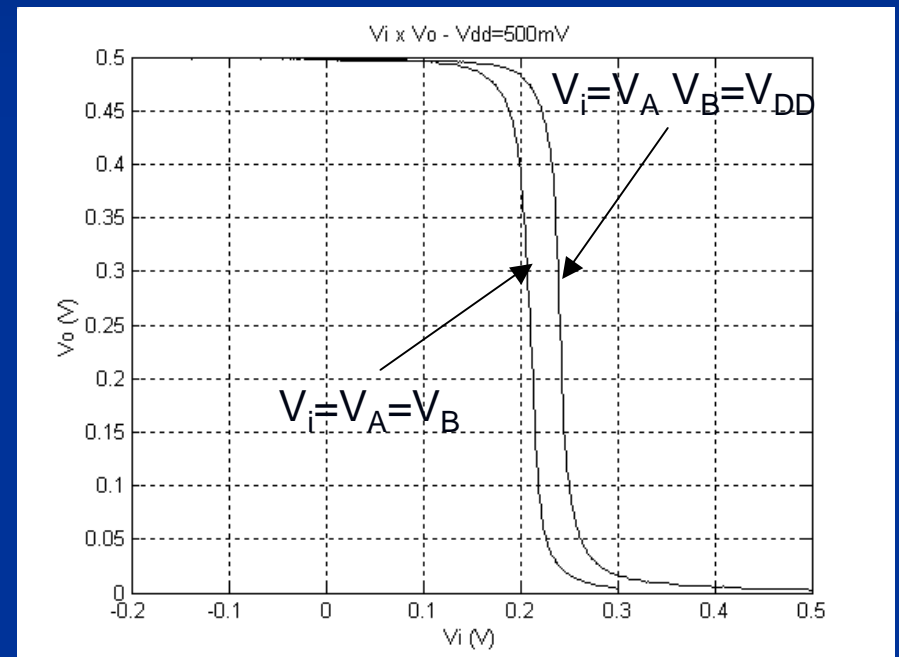


Experimental Results – INVERTER and NAND-2

0.35 μ m TSMC



INVERTER



NAND-2

Conclusion

- The operation of CMOS logic circuits in conventional CMOS technology for supply voltage as low as 250mV was shown.

Application : ULTRA-LOW POWER-CMOS